### A Naive Algorithm for Feedback Vertex Set

#### Yixin Cao (操宜新)

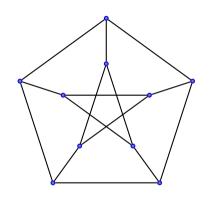
Department of Computing, Hong Kong Polytechnic University 香港理工大學 電子計算學系

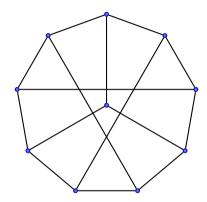
> Symposium on Simplicity in Algorithms New Orleans, LA January 10, 2018





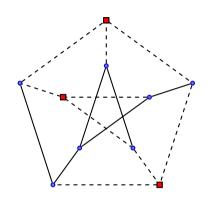
# The problem

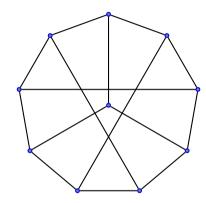




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The constraint satisfaction problem (CSP) asks for the assignment of values to variables to satisfy a set of constraints.

[Freuder 1982]: can be solved in P-time when the constraint graph is a forest.

[Dechter Pearl 1987]: one way to solve the constraint satisfaction problem is to

- lacksquare find first a minimum feedback vertex set  $V_-$  of the constraint graph,
- enumerate all possible assignments on them, and
- then solve the remaining instance.

On an instance I on p variables, it takes  $O(p^{|V_-|} \cdot |I|^{O(1)})$  time.

[Pearl 1988]: A similar application for Bayesian inference.

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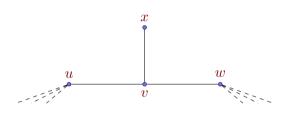
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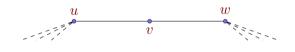
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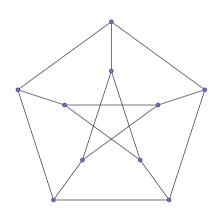
A vertex of degree 1 can always be safely deleted.



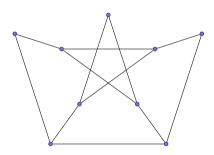
A degree-2 vertex in a solution can always be replaced with one of its neighbors.



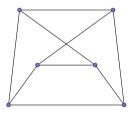














Greed ... is good. Greed is right. Greed works.

Wall street

# Algorithms

[Erdős Pósa 1962]: A graph of minimum degree  $\geq 3$  has a cycle of length  $O(\log n)$ .

- A trivial  $O(\log n)$  approximation: find a shortest cycle, remove all vertices.
- A nontrivial  $(\log k)^{O(k)}$ -time parameterized algorithm: after a polynomial kernel.

#### Large-degree vertices

[Becker Geiger 1996] [Bafna Berman Fujito 1999]: A greedy 2-approximation (Local ratio)

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### Parameterized algorithms

Algorithms running in time  $O(f(k) \cdot n^{O(1)})$ , where k is a parameter (the solution size).

Downey Fellows 1992		
Bodlaender 1994	$17(k^4)!$	
Raman et al. 2002	$\max\{12^k, (4\log k)^k\}$	
Kanj et al. 2004		
Raman et al. 2006	$(12\log k/\log\log k + 6)^k$	
Dehne et al. 2005		
Guo et al. 2006	$37.7^{k}$	
Chen et al. 2008	$5^k$	
C Chen Liu 2010	$3.83^{k}$	
Kociumaka Pilipczuk 2014	$3.62^k$	

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Chen et al. 2008	All $c^k$ algorithms use technique "iterative compression."	
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#### Context

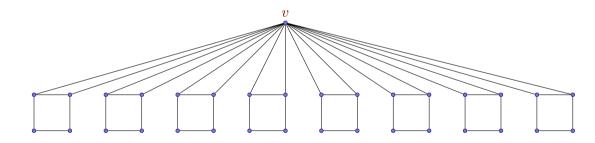
	vertex cover	feedback vertex set
to kill	edges	cycles
to make	independent set (edgeless) treewidth 0	forest (acyclic) treewidth $\leq 1$
approx	2	2
parameterized	$1.2738^{k}$	$3.62^{k}$

the *simplest nontrivial* vertex deletion problem

# The Algorithm

A vertex of the largest degree is highly likely in the solution

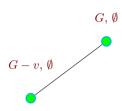
A vertex of the largest degree is highly likely in the solution, but *not* always.



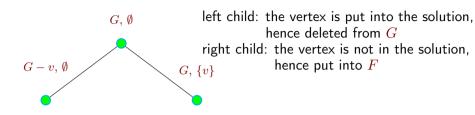


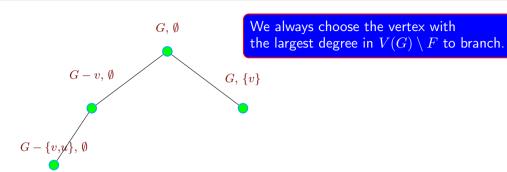


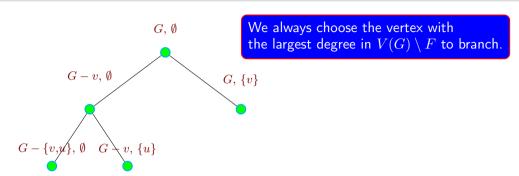
each node has two parts, the graph  ${\it G}$  and the set  ${\it F}$  of  ${\it permanent}$  vertices.

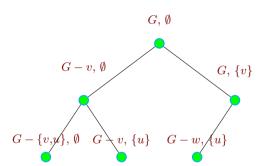


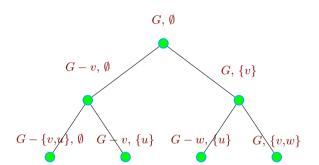
left child: the vertex is put into the solution, hence deleted from G

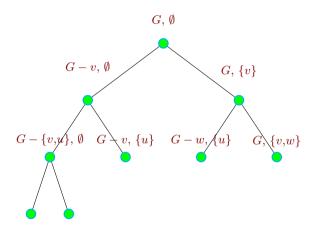


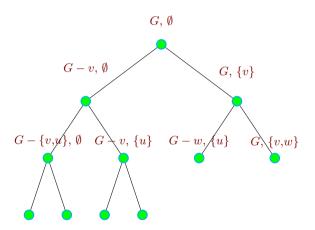


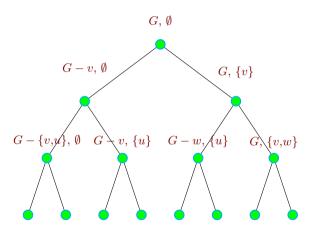






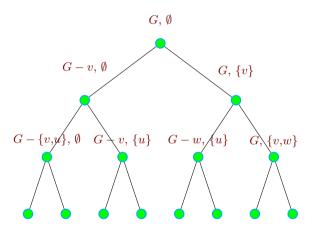






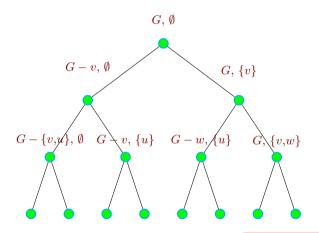
The key of the analysis is to bound the number of nodes, which boils down to bouding the depth.

### A branching algorithm



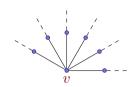
We cannot go left more than k times. We're hence focused on the right steps.

### A branching algorithm

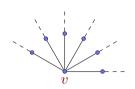


Let's fix an execution path.

# The Analysis

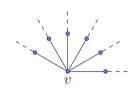


$$\sum_{v \in V(T)} d(v) = 2|E(T)| = 2|V(T)| - 2$$



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$$-2 = \sum_{v \in L} (d(v) - 2) + \sum_{v \in V(T) \backslash L} (d(v) - 2) = \sum_{v \in L} (-1) + \sum_{v \in V_3} (d(v) - 2) = \sum_{v \in V_3} (d(v) - 2) - |L|.$$

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For each  $v \notin V_{-}$ ,

- ullet either its degree is decreased from  $\geq 3$  to  $\leq 2$ ,
- or leaves are produced to "balance the equation."

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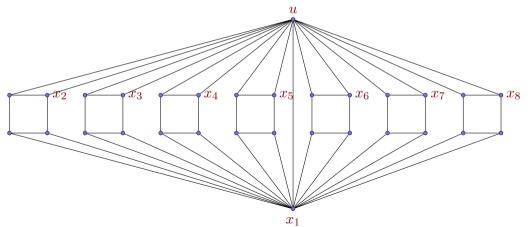
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This correlates deleted vertices and permanent vertices.

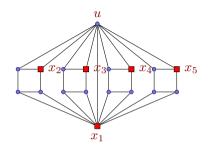
### The example

the first vertex  $x_1$  is put into  $V_-$ , second u into F, then the deletion of each  $x_i$  decreases its degree by two.

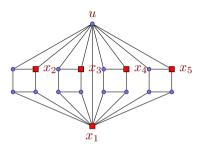


#### Algorithm invariants

- During the algorithm, the degree of no vertex can increase.
- ② There is no vertex of degree 0 or 1 in the graph when a recursive call is made.

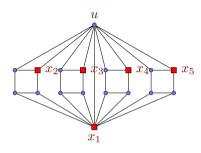


- $d^*(v)$ : the degree of v at the moment it is put into  $V_-$  or  $F_ d(v) \ge d^*(v)$ • effective decrements of the degree of a vertex  $u \in F$ : from  $d^*(u)$  to 2.
- an effective decrement is incurred by  $x_i \in V_-$  if it is after deleting  $x_i$ .  $\delta(u, x_i)$ : #effective decrements of  $u \in F$  incurred by  $x_i \in V_-$ .
- $\delta(u, x_i)$  may be larger than 1.
- $\delta(u, x_i) > 0 \quad \Rightarrow \quad u \in F \text{ when } x_i \text{ is deleted.}$



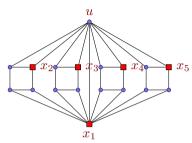
decision points:  $x_1 \rightarrow u \rightarrow x_2 \rightarrow x_3 \rightarrow x_4 \rightarrow x_5$ .

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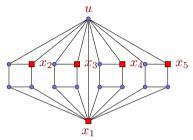
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- $\delta(u, x_i)$  may be larger than 1.
- $\delta(u, x_i) > 0 \implies u \in F$  when  $x_i$  is deleted.  $\Rightarrow d^*(u) \ge d^*(x_i)$ .



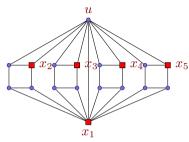
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Lemma 1: For any  $u \in F$  and  $v \in V_-$ , if  $\delta(u,v) > 0$  then  $d^*(u) \ge d^*(v)$ . Lemma 2:  $\sum_{u \in F} \delta(u,v) \le d^*(v)$  for each  $v \in V_-$ .

$$|V_{-}| = \sum_{v \in V_{-}} 1 = \sum_{v \in V_{-}} \frac{d^{*}(v)}{d^{*}(v)} \ge \sum_{v \in V_{-}} \frac{1}{d^{*}(v)} \sum_{u \in F} \delta(u, v)$$

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$$= \sum_{u \in F} \frac{d^{*}(u) - 2}{d^{*}(u)} \ge \sum_{v \in F} \frac{1}{3} = \frac{|F|}{3}$$

Lemma 3: Therefore, an execution path leading to a solution has depth at most 4k.

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Lemma 3: Therefore, an execution path leading to a solution has depth at most 4k.

#### Lemmas

Lemma 1: For any  $u\in F$  and  $v\in V_-$ , if  $\delta(u,v)>0$  then  $d^*(u)\geq d^*(v)$ . Lemma 2:  $\sum_{u\in F}\delta(u,v)\leq d^*(v)$  for each  $v\in V_-$ .

$$|V_{-}| = \sum_{v \in V_{-}} 1 = \sum_{v \in V_{-}} \frac{d^{*}(v)}{d^{*}(v)} \ge \sum_{v \in V_{-}} \frac{1}{d^{*}(v)} \sum_{u \in F} \delta(u, v)$$

$$= \sum_{v \in V_{-}} \sum_{u \in F} \frac{\delta(u, v)}{d^{*}(v)} \ge \sum_{v \in V_{-}} \sum_{u \in F} \frac{\delta(u, v)}{d^{*}(u)} = \sum_{u \in F} \frac{1}{d^{*}(u)} \sum_{v \in V_{-}} \delta(u, v)$$

$$= \sum_{v \in F} \frac{d^{*}(u) - 2}{d^{*}(u)} \ge \sum_{v \in F} \frac{1}{3} = \frac{|F|}{3},$$

Lemma 3: Therefore, an execution path leading to a solution has depth at most 4k.

We terminate all execution paths after 4k steps  $\Rightarrow O(16^k \cdot n^2)$ .

#### **Epilogue**

[Furst Gross McGeoch 1988] feedback vertex set on subcubic graphs is in P. [C. Chen Liu 2010] This can be extended to the setting  $d(v) \leq 3$  for  $v \in V(G) \setminus F$ .

Only put vertices of degree  $\geq 4$  into F, then

$$|V_-| \ge \sum_{u \in F} \frac{d^*(u) - 2}{d^*(u)} \ge \sum_{u \in F} \frac{2}{4} = \frac{|F|}{2}.$$

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We terminate all execution paths after 3k steps  $\Rightarrow O(8^k \cdot n^2)$ .  $\square$ 

#### Final remark

Beauty is the first test: there is no permanent place in the world for ugly mathematics..

G. H. Hardy

To theorists: stop ignoring successful heuristic algorithms by pretending their nonexistence!

